

LINKING SOCIAL COGNITIVE NEUROSCIENCE WITH ROBOTICS FOR RELIABILITY OF RESEARCH IN HRI



AGNIESZKA WYKOWSKA

Institute for Cognitive Systems, Technical University Munich agnieszka.wykowska@tum.de

18/10/15 A. Wykowska: Cognitive neuroscience methods for HRI research





USING METHODS OF SOCIAL COGNITIVE NEUROSCIENCE TO:

• examine fundamental mechanisms of human sensing and human cognition in human-robot interaction



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- develop models that could ultimately be implemented on robot cognitive architecture

ТШТ



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- examine implicit cognitive processes with objective measures



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Wykowska, Kajopoulos, Ramirez-Amaro, & Cheng (2015, Interaction Studies)



Pre-programmed

Institute for Cognitive Systems (ICS)

vs.

Human pre-recorded



Results:

- Sensitivity to the human-like behaviour (humanness judgment accuracy: significantly above chance, 54%)
- Lack of awareness of the correct hint



















SOCIAL ATTENTION - GAZE FOLLOWING/SHARED ATTENTION

Posner cueing

















SOCIAL ATTENTION - GAZE FOLLOWING/SHARED ATTENTION

Wiese, Wykowska, Zwickel & Müller (2012, PloS One)



Karolinska Directed Emotional Faces database (KDEF, Lundqvist, Flykt & Öhman, 1998)



(c) LSR, TU München

Task: discriminate the letter F/T







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ERPs of the EEG signal

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OBJECTIVE METHODS - APPLICATION TO CLINICAL CASES



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Wiese, Müller, & Wykowska (2014). LNAI, 8755, 370-379



















CONCLUSIONS - METHODS OF SOCIAL COGNITIVE NEUROSCIENCE IN HUMAN-ROBOT INTERACTION ALLOW FOR:

• examining implicit cognitive processes with objective measures

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- reliable, replicable and generalisable results

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- examining fundamental mechanisms of human sensing and human cognition

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- <u>reliable</u>, <u>replicable</u> and <u>generalisable</u> results
- examining <u>fundamental mechanisms</u> of human sensing and human cognition
- for clinical applications: <u>designing therapies</u> that target at specific well-understood cognitive mechanisms

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