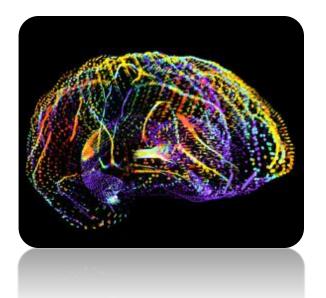
## Medical Robots for Surgery



# Tamás Haidegger, PhD



European Robotics Forum 2016 Ljubljana, Slovenia

# **Rising surgical robots**

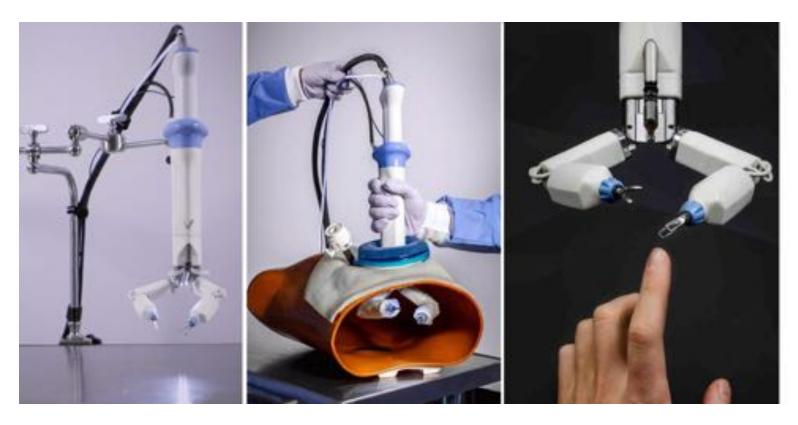
• Google + Johnson & Johnson



## **Virtual Incision**

#### University of Nebraska spin-off

D. Oleynikov et al. Since 2008 Received over \$80 m investment







# **ALF-X** Telelap

- Advanced Laparoscopy through Force-RefleCT(X)ion
- Sofar S.a.P. (Milan, IT)
- NES Academy, EU grant support
- 2006–
- Acquired by **TransEnterix** for \$100m



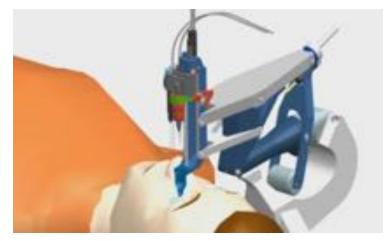


## **EurEyeCase – eye surgery robot**

- Tech. University of Eindhoven (NL) and
  - K. U. Leuven
- Tremor filtering, 1:10 motion scaling
- Haptic feedback
- RCM mechanism
- Tools of a diameter of 0.5 millimeter (forceps, scissors and drains)
- Fast instrument changing







#### Credit: Tech. University of Eindhwen



# neuroArm/Symbis

### IMRIS (2010–)

Developed by Univ. Calgary and MD Robotics

- With experience gained at the Space Station SPDM
- 1 systems, MR compatibly up to 3 T
- First brain tumor patient: 2008
- Few dozen human surgeries
- Looking for FDA clearance in 2012
  - Treating up to 120 patients

Credit: Univ. of Calgary, www.neuroarm.org





### **Robots are everywhere**

#### [Haidegger et al., RAS Special Issue, 2013]

	Pro
	> Wor
Industrial Robots	fixed
•	> Task
Caged environment	> Impl
> Apriori task definition	> Mult
Automatic execution of	proc
explicit programs	> Auto
	<ul> <li>Apriori task definition</li> <li>Automatic execution of</li> </ul>

Structured, Simple tasks,

Limited Human interaction

#### **Field Robots** ofessional Robots)

- ld Model based on d environment data
- specific commands
- licit programs
- tisensory information
- essing
  - omatic path planning

#### Personal Robots

- Autonomous agents
- Comprehension of environment through models
- Communicate with environment
- Automatic generation of programs based on tasks planned
- Understand human actions
- Follow human social norms
- Mimic human abilities and shape

#### Unstructured, Complex tasks, Natural Human interaction

Degree of Complexity

(Environment, Task and Human Interaction)



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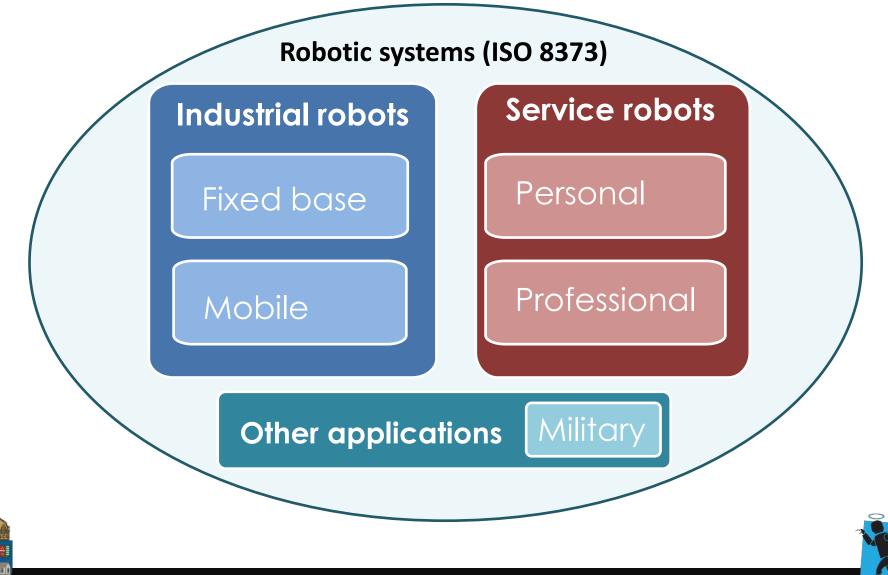


High

ymon

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#### **Domains of robotics**



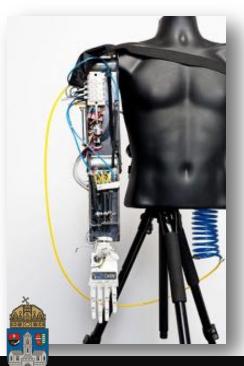
# **Medical robots**

- Visiting robots (FDA approval or RP-2/iRobot)
- Patient/goods carriers (widespread application)
- Medical delivery (GE's new radiotherapy deliv.)



# **Rehabilitation robots**

- Rehabilitation devices
- Assistive robots
- Exoskeletons
- Prosthetics
- Physiology therapy





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Credit: REHAROB cons.

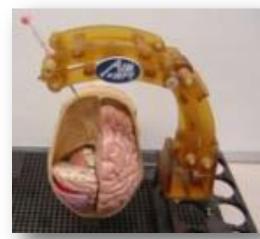


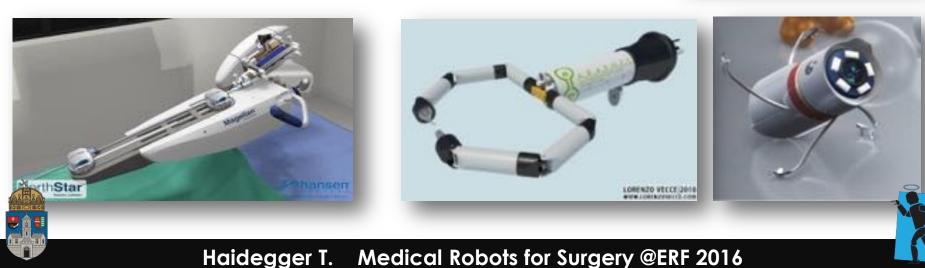


# \$20 B estimated market for IGS and medical imaging

\$20 B estimated market for MIS in 2015

\$15 B estimated for **robotic surgery** 



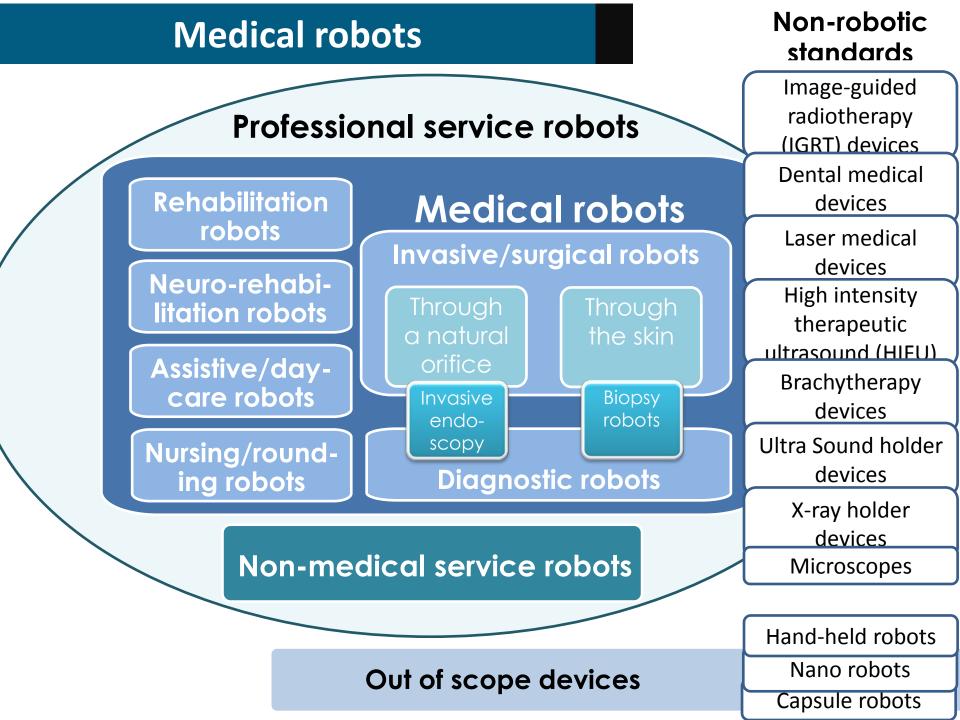


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# **Surgical robot sales**

- NeuroMate: ~30 sold (16 by ISS)
- Zeus: 50 (2002, discontinued 2003)
- ROBODOC: ~50 (37 before 2000)
- CASPAR: ~93 (discontinued in 2003)
- MAKO RIO: ~250 systems sold (2015)
- SpineAssist: 3 in the USA (07.2010)
- Renaissance: 70+ (03.2014.)
- CyberKnife: 240 (2013)
- Hansen Sensei: 130 (Q3 2012)
- ATRAS: 100+ (2014Q4)
- EndoAssist: ~100 (-2005)
- PathFinder: ~10
- Niobe: ~100?
- ROSA 55+ (2015)
- Zeego: 500+ (2014)
- da Vinci: 3500+ robots (Q1 2016)





# "Robots for medical intended use"

#### EC Machinery Directive:

 Non-medical personal care robots -> machines for performing "aiding actions, and actions contributing directly towards improvement in the quality of life of humans, except medical application"

#### EC Medical Device Directive:

 Medical robots are classified and will be regulated as *medical electrical* equipment and systems which are to be used to diagnose, treat or rehabilitate patients from medical conditions



# **Regulatory approaches**

#### European Economic Community (EU)

- CE mark (Conformité Européenne) managed by independent Notified Bodies
- ISO 9000 Quality Standards family (ISO 9001:2000) possibility of self-certification
- New: 2007/47/EC extension to 1993/42/EEC Medical Device Directive
  - more clinical data required

#### Food and Drug Administration (USA)

- Pre-Market Approval (PMA): long, thorough, expensive
- Premarket notification, 510(k): doctrine of "substantially equivalency"
- FDA Quality System Regulations (QSR)
- All surgical robots went down 510(k)

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## IEC 60601-1 updates

- supportive medical data as evidence for the safety and performance
- risk assessment and analysis even for OEMs
- Improved field monitoring (e.g., FDA MAUDE)

# 510(k) is under fire

- 510(k) Working Group
- Task Force on the Utilization of Science in Regulatory Decision Making

# Joint ISO–IEC workgroup on Medical Robot standards

- ISO/TC 299 (Robots and Robotic Devices)
- IEC/SC 62A (Common Aspects of Electrical Eq. used in Medical Practice)
- JWG 9: Joint Work Group on Standard for Medical Robot Safety
- JWG 35: Medical robots for surgery
- JWG 36: Medical robots for rehabilitation, compensation or alleviation of disease, injury or disability





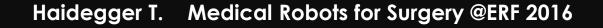
### IEC 80601-2-77

#### MEDICAL ELECTRICAL EQUIPMENT – Part 2-77:

Particular requirements for basic safety and essential performance of MEDICAL ROBOT FOR SURGERY

### **Basic issues:**

- Definitions (aligning with major standards and organizations)
- Criteria for inclusion/exclusion
  - 120+ advanced surgical robot projects identified
- Matching with other robotics standards
- Next meeting:
  - 13-16 May 2016, Gävle, Sweden





### **Inclusion issues**



# Thank you for your attention!

Follow the progress on: www.surgrob.blogspot.com



#### Andrea Bertolini, Scuola Superiore Sant'Anna

- Jan Veneman, Tecnalia
- Tamás Haidegger, Óbuda University





#### Would you accept a tele-surgery tool delivered to your home?







### **Panel questions**

#### Would you accept an automated surgery?







### **Panel questions**

#### Would you accept robotic nurses handling you?







### **Panel questions**

#### Are you afraid of robot apocalypse?

